Poised and Non-poised Hermite-Birkhoff Interpolation

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Most familiar interpolation procedures, e.g., Taylor, Lagrange and Hermite, are characterized by interpolation of function values and consecutive derivatives at one or more points. The more general problem of polynomial interpolation of scattered derivatives, including non-consecutive derivatives at several points, occur in such diverse contexts as the ascertainment of optimal quadrature formulae (see e.g., Birkhoff [2], Schoenberg [12], Karlin [5]) and in establishing unicity of solutions to two-point boundary value problems for certain vibrating mechanical systems; in this connection, see Pólya's study of the beam equation [11].

G. D. Birkhoff [2] formulated such interpolation problems in 1906. Much of the current interest in the problem springs from I. J. Schoenberg's work [12], where he defined "Hermite-Birkhoff" interpolation involving the notion of an incidence matrix. Subsequently, contributions by several authors have delineated a wide class of problems which are *poised*, *i.e.*, for which Hermite-Birkhoff (H-B) polynomial interpolation is unique. We reviewed these findings in [7] and announced new characterizations of large classes of non-poised polynomial interpolation problems. Several results on H-B spline interpolation were also stated in that work.

In this paper, proofs of these results are provided. Section 1 contains the precise statement of H–B interpolation problems, for both polynomial and spline functions. Section 2 elaborates theorems on non-poised polynomial interpolation. The analysis includes a perturbation technique from which new collections of non-poised interpolation problems can be generated out of known non-poised interpolation problems (see Theorem 2.1). Important classes of non-poised interpolation problems are described in Theorems 2.2 and 2.3.

Section 3 presents criteria for unique polynomial interpolation when linear combinations of derivatives are prescribed. Section 4 is devoted to a simplified proof of Ferguson's theorem [3] on interpolation at complex points. After reviewing the concept of a spline function in Section 5, we develop two decomposition theorems (Section 6) relevant for spline interpolation. Some necessary conditions for unique interpolation (Section 7) and sufficient con-