## On Quasiconvex Functions Which Are Homogeneous of Degree 1

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ABSTRACT. We show that there exist quasiconvex functions which are homogeneous of degree one but not convex. We also show that for quasiconvex functions f with linear growth  $\lim_{t\to\infty}\frac{f(tA)}{t}$  need not exist for all A.

**1. Introduction.** A continuous function  $f: M^{m \times n} \to \mathbf{R}$  on the space of (real) m by n matrices is called *quasiconvex* if for some open set  $D \subset \mathbf{R}^n$  one has

$$(1) \qquad \int_{D} f(F + \nabla \varphi) \, dx \geq \int_{D} f(F) \, dx \qquad \forall F \in M^{m \times n}, \, \forall \varphi \in W_{0}^{1,\infty}(D; \mathbf{R}^{m}).$$

By a simple covering argument one verifies that if (1) holds for one open set D it holds in fact for all open sets. Clearly convexity implies quasiconvexity but the converse is false if  $n \geq 2$  and  $m \geq 2$ .

The importance of quasiconvexity in the calculus of variations was first realised by Morrey ([Mo 52], [Mo 66]) who showed that quasiconvexity of f is necessary and sufficient for the lower semicontinuity of the functional

$$u \mapsto \int_D f(\nabla u(x)) dx$$

with respect to weak-\* convergence in  $W^{1,\infty}(D; \mathbf{R}^m)$ ; see Acerbi and Fusco [AF 84] or Marcellini [Ma 85] for further developments.

As (1) is a nonlocal condition it is in general very difficult to verify. This led to the consideration of the following related notions. A function f as above is called rank-1 convex if its restriction to any segment whose endpoints differ by a matrix of rank 1 is convex; it is called polyconvex if it can be written as a convex function of the minors (subdeterminants) of F. One has the implications (see [Mo 66], [Ba 77], [Da 89]):