## Integral Formulas for Hypersurfaces in Euclidean Space and Their Applications to Uniqueness Theorems

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Introduction. Let E be the Euclidean space of dimension n+1. By a hypersurface in E we mean a differentiable manifold M of dimension n and a differentiable mapping  $x: M \to E$ , whose functional matrix is everywhere of rank n. Since the strength of the differentiability assumptions will not be the issue, we suppose our manifolds and mappings to be of class  $C^{\infty}$ .

If M is compact, certain immediate integral formulas are valid. More generally, we will derive integral formulas for the hypersurface x and a second hypersurface  $x': M \to E$ . Such formulas are generalizations of well-known formulas in the theory of convex bodies, which express the mixed volumes of two convex bodies as integrals [1].

Given two compact hypersurfaces, a rigidity or uniqueness theorem gives a sufficient condition such that commutativity holds in the diagram

$$M \xrightarrow{x} E$$
 $x' \searrow E \swarrow T$ 

where T is a motion in E. Of interest in differential geometry are conditions expressed in terms of the relative curvature of the hypersurface. We review its definition as follows:

Suppose M to be oriented. Then to  $p \in M$  there is a uniquely determined unit normal vector  $\xi(p)$  at x(p). We put

(1) 
$$I = dx^2, \quad II = d\xi dx, \quad III = d\xi^2,$$

where dx,  $d\xi$  are vector-valued linear differential forms in M and multiplication is in the sense of the scalar product in E. These are three quadratic differential forms in M (the "fundamental forms"), of which I is positive definite. The eigenvalues  $k_1$ ,  $\cdots$ ,  $k_n$  of II relative to I are called the principal curvatures. If the Gauss-Kronecker curvature  $K = k_1 \cdots k_n \neq 0$ , the reciprocals  $1/k_1$ ,  $\cdots$ ,  $1/k_n$  are called the radii of principal curvature; they are the eigenvalues of II

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