## The Holonomy Group III. Metrisable Spaces\*

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1. Description of the problems. This paper is a direct continuation of [1] and [2].† It is based on the results (and symbolism) of [2]. Whenever it is necessary, these results will be quoted in the text.

Let us denote by  $L_{\omega\mu\lambda}$  either the curvature tensor  $R_{\omega\mu\lambda}$  of a volume preserving  $L_n$  or the curvature tensor  $K_{\omega\mu\lambda}$  of a Riemann space  $V_n$ . In the first case  $L_{\omega\mu\lambda}$  must satisfy the identities

(1.1) (a) 
$$L_{(\omega\mu)\lambda}^{\nu} = 0$$
, (d)  $L_{[\omega\mu\lambda]}^{\nu} = 0$ , (1.1) (c)  $L_{\omega\mu\lambda}^{\lambda} = 0$ , (d)  $\nabla_{[\xi}L_{\omega\mu]\lambda}^{\nu} = 0$ .

In the second case it must satisfy the identities (1.1a, b, c, d) and

(1.1) 
$$\begin{array}{ll} \text{(e)} & L_{\omega\mu(\lambda\nu)} = 0, \\ \\ \text{(f)} & L_{\omega\mu\lambda\nu} = L_{\lambda\nu\omega\mu} \; . \end{array}$$

Denote by  $g_{\lambda\nu}$  a symmetric tensor of rank n and by  $g^{\lambda\nu}$  its inverse,

$$(1.2) g^{\lambda \nu} g_{\lambda \mu} = \delta^{\nu}_{\mu} ,$$

and consider the following system of equations:

$$(1.3) \qquad L_{\omega\mu\lambda}^{\ \ \nu} = \partial_{\{\mu} \{ g^{\nu\alpha} (\partial_{\omega 1} g_{\alpha\lambda} + \partial_{[\lambda 1} g_{\omega]\alpha} - \partial_{[\alpha 1} g_{\omega]\lambda} \} + \frac{1}{2} g^{\nu\beta} (\partial_{\alpha} g_{\beta [\mu} + \partial_{[\mu} g_{\alpha\beta]} - \partial_{\beta} g_{\alpha [\mu}) g^{\alpha\delta} (\partial_{\omega 1} g_{\lambda\delta} + \partial_{[\lambda 1} g_{\omega]\delta} - \partial_{[\delta 1} g_{\omega]\lambda}).$$

If  $g_{\lambda\mu}$  is not known and  $L_{\omega\mu\lambda}^{\nu}$  is given, (1.3) represents a system of differential equations for  $g_{\lambda\mu}$ . Then one of our problems may be formulated as follows:

- 1(a). One has to find necessary and sufficient conditions for (1.3) to admit at least one solution  $g_{\lambda_{\nu}}$ .
- 1(b). If these conditions are satisfied, one has to find the explicit form of at least one solution  $g_{\lambda_{r}}$ .
  - 1(c). If one solution is given, one has to find the explicit form of all solutions.

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<sup>†</sup>These papers will be denoted by I and II.